

**Amendments to the Claims:**

This listing of claims will replace all prior versions, and listings, of claims in the application:

Claims 1-11 (cancelled).

Claim 12 (previously presented) A method for monitoring a first control value ( $I_{nom}$ ) for overshooting or undershooting of a threshold value ( $I_{max}$ ), with the first control value ( $I_{nom}$ ) being used for controlling an apparatus (3); having the following steps:

- a) determination of the threshold value ( $I_{max}$ ) from instantaneous value ( $I_s$ ) of the first control value ( $I_{nom}$ ) when the apparatus (3) reaches a predetermined operating state, and
- b) monitoring the first control value ( $I_{nom}$ ) for overshooting or undershooting of the determined threshold value ( $I_{max}$ ) when the apparatus (3) reaches the predetermined operating state.